

Please check that this question paper contains 09 questions and 02 printed pages within first ten minutes.

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[Total No. of Questions: 09]

[Total No. of Pages: 02]

Uni. Roll No.

09 JAN 2023

Program: B.Tech. ME (Batch 2018 onward)

Semester: 5th

Name of Subject: Industrial Automation and Robotics

Subject Code: PCME-114

Paper ID: 16381

Time Allowed: 03 Hours

Max. Marks: 60

NOTE:

- 1) Parts A and B are compulsory.
- 2) Part-C has Two Questions Q8 and Q9. Both are compulsory, but with internal choice.
- 3) Any missing data may be assumed appropriately.

Part – A

[Marks: 02 each]

Q1.

- (a) What is hard automation?
- (b) Which different logic can be used in pneumatic circuit design?
- (c) What do you understand by the work envelope of a robot?
- (d) Distinguish between hydraulic and pneumatic systems.
- (e) Draw the symbol of the 5/3 solenoid-operated spring return DC valve.
- (f) Give the symbol of the NOR gate with the truth table.

Part – B

[Marks: 04 each]

- Q2. Explain the architecture of a Programmable logic controller with the help of a neat sketch.
- Q3. A double-acting cylinder is to extend when a push button is operated. Upon release of the push button, the cylinder is to retract. The cylinder is of a small bore (25 mm diameter), requiring a small flow rate to operate at the correct speed. Draw the circuit

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diagram for the problem. Designate the valves and indicate the numbering system for the connections (ports).

- Q4. Discuss the use of a vibratory bowl feeder with the help of a diagram.
- Q5. What is meant by the Coanda effect? Sketch any fluidic device and explain its operation—state its applications.
- Q6. Discuss the industrial applications of robots.
- Q7. What are the different types of end effectors used in robots?

Part – C

[Marks: 12 each]

- Q8. How is machine vision implemented in robots? Discuss the advantages and constraints of machine vision integration in robotics.

OR

Compare the pneumatic, hydraulic and electric drives to power the robot.

- Q9. What is a control system? Show, with the help of a diagram, the difference between an open-loop control system and a closed-loop control system.

OR

Draw meter in circuit and meter out circuit, and explain it.
